# Liangkai Liu

Research Fellow, University of Michigan

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## **Research Interests**

Embedded AI, Cyber-Physical Systems, Autonomous Driving, Edge Computing, Robotics.

## Experience

<ul> <li>University of Michigan Research Fellow</li> <li>Mentor: Prof. Kang G. Shin</li> </ul>	September 2023 - Present Ann Arbor, MI, USA
<ul> <li>University of Delaware Postdoctoral Researcher</li> <li>Mentor: Prof. Weisong Shi</li> </ul>	May 2023 - August 2023 Newark, DE, USA
Argonne National Laboratory     Research Intern	May 2021 - August 2021 Lemont, IL, USA
Argonne National Laboratory     Research Intern	May 2020 - August 2020 Lemont, IL, USA
Education	

• Wayne State University Ph.D. in Computer Science

- Advisor: Prof. Weisong Shi
- Dissertation: Predictable DNN Inference for Autonomous Driving.
- Xidian University B.S. in Telecommunication Engineering

August 2013 - June 2017 Xi'an, China

January 2018 - May 2023

Detroit, MI, USA

# Awarded Grant

 <u>NSF CSR: Small:</u> Predictable Multi-Tenant DNN Inference for Autonomous Driving, 2024 My Role: Co-Principal Investigator (My share: \$300,000)
 PI: Weisong Shi Awarded amount: \$600,000 (10/1/2024 - 9/30/2027)
 Grant number: 2343601

## **PUBLICATIONS**

 $C{=}Conference, J{=}Journal, B{=}Book, S{=}In \ Submission$ 

Google Scholar (as of May 31, 2025): 2,264 citations, H-Index: 18, i10-Index: 21.
25 research articles and 1 book, including 15 as first author: eight appearing in flagship conferences (two in RTSS, one in ICCAD, two in SEC, one in ICRA, and two in HotEdge) and three in premier journals (one each in TITS, IoTJ, and IWC).

# Conferences

[C15] Liangkai Liu, Jinkyu Lee, and Kang G. Shin, "RT-BEV: Enhancing Real-Time BEV Perception for Autonomous Vehicles," in *Proceedings of the IEEE Real-Time Systems Symposium* (*RTSS*), 2024.

[C14] Liangkai Liu\*, Chao Wu\*, Yifan Gong\*, Mengquan Li, Yushu Wu, Xuan Shen, Zhimin Li, Geng Yuan, Weisong Shi, and Yanzhi Wang, "AyE-Edge: Automated Deployment Space Search Empowering Accuracy yet Efficient Real-Time Object Detection on the Edge," in *International Conference on Computer-Aided Design* (*ICCAD*), 2024. (\*Equal contribution)

[C13] Yifan Gong, Yushu Wu, Zheng Zhan, Liangkai Liu, Chao Wu, Xulong Tang, and Yanzhi Wang, "LOTUS: Learning-Based Online Thermal and Latency Variation Management for Two-Stage Detectors on Edge Devices," in *Design Automation Conference (DAC)*, 2024.

[C12] Liangkai Liu, Ren Zhong, Aaron Willcock, Nathan Fisher, and Weisong Shi, "An Open Approach to Energy-Efficient Autonomous Mobile Robots," in *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA)*, 2023.

[C11] Liangkai Liu, Yanzhi Wang, and Weisong Shi, "Understanding Time Variations of DNN Inference in Autonomous Driving," in *MLSys Workshop on Benchmarking Machine Learning Workloads on Emerging Hardware* (*MLBench*), 2023.

[C10] Abdullah Al Arafat, Sudharsan Vaidhun, Liangkai Liu, Kecheng Yang, and Zhishan Guo, "Compositional Mixed-Criticality Systems with Multiple Executions and Resource-Budgets Model," in *Proceedings of the IEEE Real-Time and Embedded Technology and Applications Symposium (RTAS)*, 2023.

**[C9] Liangkai Liu**, Zheng Dong, Yanzhi Wang, and Weisong Shi, "Prophet: Realizing a Predictable Real-time Perception Pipeline for Autonomous Vehicles," in *Proceedings of the IEEE Real-Time Systems Symposium* (*RTSS*), 2022.

**[C8] Liangkai Liu**, Baofu Wu, and Weisong Shi, "A Comparison of Communication Mechanisms in Vehicular Edge Computing," in *USENIX Workshop on Hot Topics in Edge Computing (HotEdge)*, 2020.

**[C7] Liangkai Liu**, Jiamin Chen, Marco Brocanelli, and Weisong Shi, "E2M: An Energy-Efficient Middleware for Computer Vision Applications on Autonomous Mobile Robots," in *ACM/IEEE Symposium on Edge Computing* (SEC), 2019.

**[C6]** Xingzhou Zhang, Mu Qiao, **Liangkai Liu**, and Weisong Shi, "Collaborative Cloud-Edge Computation for Personalized Driving Behavior Modeling," in *ACM/IEEE Symposium on Edge Computing* (*SEC*), 2019.

**[C5]** Yifan Wang, **Liangkai Liu**, Xingzhou Zhang, and Weisong Shi, "HydraOne: An Indoor Experimental Research and Education Platform for CAVs," in *USENIX Workshop on Hot Topics in Edge Computing* (*HotEdge*), 2019.

**[C4]** Xingzhou Zhang, Yifan Wang, Sidi Lu, **Liangkai Liu**, Lanyu Xu, and Weisong Shi, "OpenEI: An Open Framework for Edge Intelligence," in *Proceedings of the IEEE International Conference on Distributed Computing Systems (ICDCS)*, 2019. (150+ citations)

**[C3] Liangkai Liu**, Xingzhou Zhang, Mu Qiao, and Weisong Shi, "SafeShareRide: Edge-based Attack Detection in Ridesharing Services," in *ACM/IEEE Symposium on Edge Computing* (SEC), 2018.

**[C2] Liangkai Liu**, Xingzhou Zhang, Mu Qiao, and Weisong Shi, "SafeShareRide: Edge-based Attack Detection in Ridesharing Services," in *USENIX Workshop on Hot Topics in Edge Computing (HotEdge)*, 2018.

[C1] Qingyang Zhang, Yifan Wang, Xingzhou Zhang, Liangkai Liu, Xiaopei Wu, Weisong Shi, and Hong Zhong, "OpenVDAP: An Open Vehicular Data Analytics Platform for CAVs," in *Proceedings of the IEEE International Conference on Distributed Computing Systems (ICDCS)*, 2018. (120+ citations)

### Books

[B1] Weisong Shi and Liangkai Liu. Computing Systems for Autonomous Driving. November 2021, Springer.

# Journals

[J6] Liangkai Liu, Yanzhi Wang, and Weisong Shi, "CPT: A Configurable Predictability Testbed for DNN Inference in AVs," in Tsinghua Science and Technology, September 2024.

[J5] Liangkai Liu, Wei Li, Dawei Wang, Yi Wu, Ruigang Yang, and Weisong Shi, "Fuel Rate Prediction for Autonomous Heavy-Duty Trucks," in IEEE Transactions on Intelligent Transportation Systems (TITS), 2023.

[J4] Liangkai Liu, Shaoshan Liu, and Weisong Shi, "4C: A Computation, Communication, and Control Co-Design Framework for CAVs," in IEEE Wireless Communications (IWC), Vol. 28, No. 4, pp. 42-48, August 2021.

[J3] Tianze Wu, Baofu Wu, Sa Wang, Liangkai Liu, Shaoshan Liu, Yungang Bao, and Weisong Shi, "Oops! It's Too Late. Your Autonomous Driving System Needs a Faster Middleware," IEEE Robotics and Automation Letters (RA-L), Vol. 6, No. 4, pp. 7301-7308, July 2021.

[J2] Liangkai Liu, Sidi Lu, Ren Zhong, Baofu Wu, Yongtao Yao, Qingyang Zhang, and Weisong Shi, "Computing Systems for Autonomous Driving: State-of-the-Art and Challenges", in IEEE Internet of Things Journal (IoTJ), Vol. 8, No. 8, pp. 6469-6486, December 2020. (400+ citations)

[J1] Shaoshan Liu, Liangkai Liu, Jie Tang, Bo Yu, Yifan Wang, and Weisong Shi, "Edge Computing for Autonomous Driving: Opportunities and Challenges," Proceedings of the IEEE, Vol. 107, No. 8, pp. 1697-1716, August 2019. (750+ citations)

## **Research Projects**

- Safe and Predictable Perception Pipeline for Autonomous Vehicles September 2023 - present Mentor: Kang G. Shin University of Michigan • RT-BEV: the first framework co-optimizes message communication and object detection with dynamic region of interests (ROIs) for improving real-time e2e BEV perception without sacrificing accuracy. (RTSS'24) • PP-DNN: models critical regions into variable sizes ROIs to achieve predictable perception pipeline. Energy-Efficient Cyber Physical Systems September 2023 - present University of Michigan Mentor: Kang G. Shin • pNay: a novel power-management system designed to enhance the power/energy-efficiency of Autonomous
  - Mobile Robots (AMRs) by jointly optimizing their physical/mechanical and cyber subsystems.
  - eXR: an energy-efficient middleware designed for extended reality applciation based on coordianted management of feature extraction, resource scheduling, and DVFS configurations.
- DNN Inference Time Variations for Autonomous Vehicles January 2020 - August 2023 Wayne State University, University of Delaware
- PDNN Grant: Awarded a research grant from NSF for studying predictable multi-tenant DNNs inferece time variations for autonomous vehicles. (NSF Grant)

Mentor: Weisong Shi

- Prophet: identify root causes for DNN inference time variations and propose an early-exit cooridnation system to optimization the inference pipeline for autonomous vehicles. (RTSS'22, RTAS'23)
- CPT: propose a reconfigurable testbed for profiling the DNN inference time and accuracy variations for autonomous vehicles under various traffic environments. (Tsinghua Science and Technology, 2023)
- Analyze the time variation in DNN inference in fine granularity from six perspectives: data, I/O, model, runtime, hardware, and end-to-end perception system. (MLBench'23)

#### Energy/Fuel Efficient Autonomous Trucking/Driving May 2019 - May 2023 Wayne State University Mentor: Weisong Shi • Create a fuel dataset using the truck's engine management system (EMS) and Instant Fuel Meter (IFM) and propose ML-based prediction model for real-time fuel prediction and integrated into predictive planning for autonomous trucking. (IEEE TITS, 2023) • Develope a customized AMR called Donkey, which has the capability for millisecond-level end-to-end power profiling. Propose a comprehensive energy prediction model that provides real-time energy consumption for each component of the autonomous mobile robots. (ICRA'23) • E2M: an energy-efficient middleware software stack for optimizing the computing stack of autonomous mobile robots. (SEC'19) · Open Platforms for Connected and Autonomous Vehicles May 2018 - December 2021 Wayne State University Mentor: Weisong Shi • Led the development of a level-4 autonomous driving vehicle (Hydra) based on Autoware and DriveWorks with a complete sensor suite (LiDAR, camera, radar, GNSS, etc.). • Designed and implemented Equinox, a Road Side Unit (RSU) with heterogeneous computation and communication resources. Developed a vehicular edge computing (VEC) prototype supporting WiFi, DSRC, and LTE; compared their performance using real CAV applications. (HotEdge'20, MeterCAD'20) • Designed HydraOne from scratch, an indoor research and education platform. (HotEdge'19) **Edge Computing Enabled Applications for Public Safety** January 2018 - December 2018

- Wayne State UniversityMentor: Weisong Shi• SafeShareRide: an edge-based real-time attack detection system in ridesharing services. (HotEdge'18, SEC'18)
- AutoVAPS, an edge-based reference architecture for privacy-preserving data sharing and access on law enforcement vehicles. (CPS WEEK'18 Workshop)

## HONORS AND AWARDS

•	<b>Department Travel Award for Outstanding Conference Publications</b> Wayne State University	2023
•	<b>RTSS Student Travel Grant</b> IEEE Real-Time Systems Symposium	2022
•	<b>Department Travel Award for Outstanding Conference Publications</b> Wayne State University	2022
•	<b>NSF ACM/IEEE Symposium on Edge Computing Student Travel Grant</b> <i>National Science Foundation</i>	2019, 2018, 2021
•	<b>Top Ten Seniors Award</b> <i>Xidian University</i>	2016
•	First Prize, CETC-10 Literature Review Contest CETC-10, Xidian University	2016

## **TEACHING EXPERIENCE**

•	Guest lecture, Building Predictable and Power-Efficient Autonomous Cyber-Physical Systems	2024
	University of Michigan, Oakland University	
•	Guest lecture, Robot Platforms for CPS Research	2024
	University of Michigan, EECS-571	
•	Guest lecture, Building Predictable and Efficient System for Autonomous Vehicles/Robots	2024
	University of Michigan, University of North Texas, California Polytechnic State University	

•	Seminar talk: Introduction to Autonomous Driving HensHack at University of Delaware	2023
•	<b>Computing systems for connected and autonomous driving</b> UIUC physical AI group	2022
•	<b>Teaching Assistant, Introduction to Java Programming</b> Wayne State University	2018

### **Mentoring Experience**

•	Sanjith Udupa Novi High School student; now undergraduate at MIT	Mentored: 2022/2023 first-authored paper
•	Mingyu Guo Undergraduate at the University of Wisconsin–Madison; now Ph.D. at University of Delawar	Mentored: 2023 re
•	<b>Yuchen Chueh</b> Admitted to Master's Program at Carnegie Mellon University, now at Nvidia	Mentored: 2020
•	<b>Justin Baskaran</b> Backend Software Engineer at General Motors	Mentored: 2018

#### **PROFESSIONAL SERVICES**

- Publication Chair, ACM/IEEE Symposium on Edge Computing, 2025.
- **Program Committee**, The 3rd IEEE International Conference on Mobility: Operations, Services, and Technologies (MOST), 2024/2025
- Program Committee, Workshop on Compute Platforms for Autonomous Vehicles (CAV), ASPLOS 2024
- **Program Committee**, The 21th ACM Conference on Embedded Networked Sensor Systems (SenSys 2023) Posters & Demos
- Reviewer, International Conference on Computer Vision (ICCV), 2025
- Reviewer, IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR), 2024/2025
- Reviewer, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2022/2023/2024
- Reviewer, IEEE International Conference on Robotics and Automation (ICRA), 2023
- Web Chair, The 30th Annual International Conference on Mobile Computing and Networking (MobiCom 2024)
- Committee Member, Technical Steering Committee of the Autoware Foundation, October 2022 December 2023
- Verified and Recognized Reviewer: IEEE Communications Magazine, Proceedings of the IEEE, IEEE Transactions on Vehicular Technology, IEEE Vehicular Technology Magazine, IEEE Transactions on Services Computing, IEEE Internet of Things Journal, IEEE Network Magazine, IEEE Internet Computing, IEEE Open Journal of Circuits and Systems, IEEE Transactions on Network Science and Engineering, IEEE Transactions on Intelligent Transportation Systems, and IEEE Robotics and Automation Letters.

#### References

#### 1. Kang G. Shin

Kevin and Nancy O'Connor Professor of Computer Science University of Michigan Email: kgshin@umich.edu Phone: +1-734-763-0391 *Relationship: Postdoc Mentor* 

#### 2. Weisong Shi

Alumni Distinguished Professor and Chair, Department of Computer and Information Sciences University of Delaware Email: weisong@udel.edu Phone: +1-302-831-7603 *Relationship: PhD Advisor* 

#### 3. Chengmo Yang

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#### 4. Yanzhi Wang

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#### 5. Marco Brocanelli

Assistant Professor, Electrical and Computer Engineering Ohio State University Email: brocanelli.1@osu.edu *Relationship: Collaborator*