

# Liangkai Liu

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Ann Arbor, Michigan - 48109, USA

## RESEARCH INTERESTS

Area: **real-time cyber-physical systems, computing systems for autonomous driving, edge computing, robotics.**

Topics: **autonomous driving** (computing systems, predictable perception, time variations), **robotic systems** (energy efficient middleware, autonomous mobile robots), **intelligent transportation systems** (autonomous trucking, connected vehicles, vehicular communications), **edge computing** (public safety applications).

## EXPERIENCE

- **University of Michigan** *September 2023 - Present*  
Ann Arbor, MI, USA  
*Research Fellow*
  - **Mentor: Prof. Kang Shin**
- **University of Delaware** *May 2023 - August 2023*  
Newark, DE, USA  
*Postdoctoral Researcher*
  - **Mentor: Prof. Weisong Shi**
- **Argonne National Laboratory** *May 2021 - August 2021*  
Lemont, IL, USA  
*Research Intern*
- **Argonne National Laboratory** *May 2020 - August 2020*  
Lemont, IL, USA  
*Research Intern*
- **NetEase Hangzhou Research Center** *July 2017 - December 2017*  
Hangzhou, China  
*Research Intern*

## EDUCATION

- **Wayne State University** *January 2018 - May 2023*  
Detroit, MI, USA  
*Ph.D. in Computer Science (GPA: 3.98/4.00)*
  - **Advisor:** Prof. Weisong Shi
  - **Dissertation:** *Predictable DNN Inference for Autonomous Driving.*
- **Xidian University** *August 2013 - June 2017*  
Xi'an, China  
*B.S. in Telecommunication Engineering (GPA: 3.25/4.00)*

## GRANT AS PI/CO-PI

- **Predictable Multi-Tenant DNN Inference for Autonomous Driving, 2024**  
**National Science Foundation CSR: Small**  
**My Role:** Co-Principal Investigator  
Awarded to: University of Delaware  
PI: Weisong Shi  
Awarded amount: \$600,000 (10/1/2024 - 9/30/2027)  
Grant number: **2343601**

**FULL LIST OF PUBLICATIONS**

C=CONFERENCE, J=JOURNAL, B=BOOK, S=IN SUBMISSION

**Google Scholar** (as of Oct. 21, 2024): **1,852** citations, **H-Index: 16**, **i10-Index: 20**.

**24** research articles and **1** book, including **14** as first author: **eight** appearing in flagship conferences (two in RTSS, one in ICCAD, two in SEC, one in ICRA, and two in HotEdge) and **three** in premier journals (one each in TITS, IoTJ, and IWC).

**First-Author Publications**

[C17] **Liangkai Liu**, Jinkyu Lee, and Kang G. Shin, "RT-BEV: Enhancing Real-Time BEV Perception for Autonomous Vehicles," in *Proceedings of the IEEE Real-Time Systems Symposium (RTSS)*, 2024.

[C16] Chao Wu\*, Yifan Gong\*, **Liangkai Liu\***, Mengquan Li, Yushu Wu, Xuan Shen, Zhimin Li, Geng Yuan, Weisong Shi, and Yanzhi Wang, "AyE-Edge: Automated Deployment Space Search Empowering Accuracy yet Efficient Real-Time Object Detection on the Edge," in *International Conference on Computer-Aided Design (ICCAD)*, 2024. (\*Equal contribution)

[C15] **Liangkai Liu**, Ren Zhong, Aaron Willcock, Nathan Fisher, and Weisong Shi, "An Open Approach to Energy-Efficient Autonomous Mobile Robots," in *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA)*, 2023.

[C14] **Liangkai Liu**, Zheng Dong, Yanzhi Wang, and Weisong Shi, "Prophet: Realizing a Predictable Real-time Perception Pipeline for Autonomous Vehicles," in *Proceedings of the IEEE Real-Time Systems Symposium (RTSS)*, 2022.

[C13] **Liangkai Liu**, Baofu Wu, and Weisong Shi, "A Comparison of Communication Mechanisms in Vehicular Edge Computing," in *USENIX Workshop on Hot Topics in Edge Computing (HotEdge)*, 2020.

[C12] **Liangkai Liu**, Yongtao Yao, Ruijun Wang, Baofu Wu, and Weisong Shi, "Poster: Equinox: A Road-Side Edge Computing Experimental Platform for CAVs," in *Proceedings of the IEEE International Conference on Connected and Autonomous Driving (MetroCAD)*, 2020.

[C11] **Liangkai Liu**, Jiamin Chen, Marco Brocanelli, and Weisong Shi, "E2M: An Energy-Efficient Middleware for Computer Vision Applications on Autonomous Mobile Robots," in *ACM/IEEE Symposium on Edge Computing (SEC)*, 2019.

[C10] **Liangkai Liu**, Xingzhou Zhang, Qingyang Zhang, Andrew Weinert, Yifan Wang, and Weisong Shi, "AutoVAPS: an IoT-Enabled Public Safety Service on Vehicles," in *CPSWEEK Workshop on Science of Smart City Operations and Platforms Engineering*, 2019.

[C9] **Liangkai Liu**, Xingzhou Zhang, Mu Qiao, and Weisong Shi, "SafeShareRide: Edge-based Attack Detection in Ridesharing Services," in *ACM/IEEE Symposium on Edge Computing (SEC)*, 2018.

[C8] **Liangkai Liu**, Xingzhou Zhang, Mu Qiao, and Weisong Shi, "SafeShareRide: Edge-based Attack Detection in Ridesharing Services," in *USENIX Workshop on Hot Topics in Edge Computing (HotEdge)*, 2018.

[J7] **Liangkai Liu**, Yanzhi Wang, and Weisong Shi, "CPT: A Configurable Predictability Testbed for DNN Inference in AVs," *Tsinghua Science and Technology*, September 2024.

[J6] **Liangkai Liu**, Wei Li, Dawei Wang, Yi Wu, Ruigang Yang, and Weisong Shi, "Fuel Rate Prediction for Autonomous Heavy-Duty Trucks," *IEEE Transactions on Intelligent Transportation Systems (TITS)*, 2023.

[J5] **Liangkai Liu**, Shaoshan Liu, and Weisong Shi, "4C: A Computation, Communication, and Control Co-Design Framework for CAVs," *IEEE Wireless Communications (IWC)*, Vol. 28, No. 4, pp. 42-48, August 2021.

[J4] **Liangkai Liu**, Sidi Lu, Ren Zhong, Baofu Wu, Yongtao Yao, Qingyang Zhang, and Weisong Shi, "Computing Systems for Autonomous Driving: State-of-the-Art and Challenges", *IEEE Internet of Things Journal (IoTJ)*, Vol. 8, No. 8, pp. 6469-6486, December 2020.

## Books

[B1] Weisong Shi and **Liangkai Liu**. *Computing Systems for Autonomous Driving*. November 2021, Springer.

## In Submission

[S2] **Liangkai Liu**, Kang G. Shin, Chengmo Yang, and Weisong Shi, Predictable DNN Inference for Autonomous Vehicles, Submitted to **RTAS 2025**.

[S1] **Liangkai Liu**, Weisong Shi, and Kang G. Shin, Power-Efficient Navigation of Autonomous Mobile Robots, Submitted to **EuroSys 2025**.

## Co-Author Publications

[C7] Noah T. Curran, Minkyong Cho, Ryan Feng, **Liangkai Liu**, Brian Jay Tang, Pedram MohajerAnsari, Alkim Domeke, Mert D. Pesé, and Kang G. Shin, "Achieving the Safety and Security of the End-to-End AV Pipeline", in *the 1st Cyber Security in Cars Workshop (CSCS '24)*, Salt Lake City, UT, October 2024.

[C6] Yifan Gong, Yushu Wu, Zheng Zhan, **Liangkai Liu**, Chao Wu, Xulong Tang, and Yanzhi Wang, "LOTUS: Learning-Based Online Thermal and Latency Variation Management for Two-Stage Detectors on Edge Devices," in *Design Automation Conference (DAC)*, 2024.

[C5] Abdullah Al Arafat, Sudharsan Vaidhun, **Liangkai Liu**, Kecheng Yang, and Zhishan Guo, "Compositional Mixed-Criticality Systems with Multiple Executions and Resource-Budgets Model," in *Proceedings of the IEEE Real-Time and Embedded Technology and Applications Symposium (RTAS)*, 2023.

[C4] Yifan Wang, **Liangkai Liu**, Xingzhou Zhang, and Weisong Shi, "HydraOne: An Indoor Experimental Research and Education Platform for CAVs," in *USENIX Workshop on Hot Topics in Edge Computing (HotEdge)*, 2019.

[C3] Xingzhou Zhang, Yifan Wang, Sidi Lu, **Liangkai Liu**, Lanyu Xu, and Weisong Shi, "OpenEI: An Open Framework for Edge Intelligence," in *Proceedings of the IEEE International Conference on Distributed Computing Systems (ICDCS)*, 2019.

[C2] Xingzhou Zhang, Mu Qiao, **Liangkai Liu**, and Weisong Shi, "Collaborative Cloud-Edge Computation for Personalized Driving Behavior Modeling," in *ACM/IEEE Symposium on Edge Computing (SEC)*, 2019.

[C1] Qingyang Zhang, Yifan Wang, Xingzhou Zhang, **Liangkai Liu**, Xiaopei Wu, Weisong Shi, and Hong Zhong, "OpenVDAP: An Open Vehicular Data Analytics Platform for CAVs," in *Proceedings of the IEEE International Conference on Distributed Computing Systems (ICDCS)*, 2018.

[J3] Tianze Wu, Baofu Wu, Sa Wang, **Liangkai Liu**, Shaoshan Liu, Yungang Bao, and Weisong Shi, "Oops! It's Too Late. Your Autonomous Driving System Needs a Faster Middleware," *IEEE Robotics and Automation Letters (RA-L)*, Vol. 6, No. 4, pp. 7301-7308, July 2021.

[J2] Congfeng Jiang, Tiantian Fan, Honghao Gao, Weisong Shi, **Liangkai Liu**, Christophe Cerin, and Jian Wan, "Energy-Aware Edge Computing: A Survey," *Computer Communications*, Vol. 151, No. 1, pp. 556-580, February 2020.

[J1] Shaoshan Liu, **Liangkai Liu**, Jie Tang, Bo Yu, Yifan Wang, and Weisong Shi, "Edge Computing for Autonomous Driving: Opportunities and Challenges," *Proceedings of the IEEE*, Vol. 107, No. 8, pp. 1697-1716, August 2019.

## RESEARCH PROJECTS

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- **Safe and Predictable Perception Pipeline for Autonomous Vehicles**  
*University of Michigan*

  - RT-BEV, the first framework designed to co-optimize message communication and object detection with dynamic region of interests (ROIs) for improving real-time e2e BEV perception without sacrificing accuracy. ([RTSS'24](#))
  - PP-DNN: Propose to model critical regions into variable sizes ROIs to achieve predictable perception pipeline. ([under review by RTAS'25](#))

*September 2023 - present*  
**Mentor:** Kang G. Shin
  
- **Energy-Efficient Cyber Physical Systems**  
*University of Michigan*

  - pNav: a novel power-management system designed to enhance the power/energy-efficiency of Autonomous Mobile Robots (AMRs) by jointly optimizing their physical/mechanical and cyber subsystems. ([under review by EuroSys'25](#))

*September 2023 - present*  
**Mentor:** Kang G. Shin
  
- **DNN Inference Time Variations for Autonomous Vehicles**  
*Wayne State University, University of Delaware*

  - PDNN Grant: Awarded a research grant from NSF for studying predictable multi-tenant DNNs inference time variations for autonomous vehicles. ([NSF Grant](#))
  - Prophet: identify root causes for DNN inference time variations and propose an early-exit coordination system to optimization the inference pipeline for autonomous vehicles ([RTSS'22](#), [RTAS'23](#)).
  - CPT: propose a reconfigurable testbed for profiling the DNN inference time and accuracy variations for autonomous vehicles under various traffic environments. ([Tsinghua Science and Technology](#))
  - Analyze the time variation in DNN inference in fine granularity from six perspectives: data, I/O, model, runtime, hardware, and end-to-end perception system. ([MLBench'23](#))

*January 2020 - August 2023*  
**Mentor:** Weisong Shi
  
- **Energy/Fuel Efficient Autonomous Trucking/Driving**  
*Wayne State University*

  - Create a fuel dataset using the truck's engine management system (EMS) and Instant Fuel Meter (IFM) and propose ML-based prediction model for real-time fuel prediction and integrated into predictive planning for autonomous trucking. ([IEEE TITS](#))
  - Develop a customized AMR called Donkey, which has the capability for millisecond-level end-to-end power profiling. Propose a comprehensive energy prediction model that provides real-time energy consumption for each component of the autonomous mobile robots. ([ICRA'23](#)).
  - E2M: an energy-efficient middleware software stack for optimizing the computing stack of autonomous mobile robots ([SEC'19](#)).

*May 2019 - May 2023*  
**Mentor:** Weisong Shi
  
- **Open Platforms for Connected and Autonomous Vehicles**  
*Wayne State University*

  - Led the development of a level-4 autonomous driving vehicle ([Hydra](#)) based on Autoware and DriveWorks with a complete sensor suite (LiDAR, camera, radar, GNSS, etc.).
  - Designed and implemented [Equinox](#), a Road Side Unit (RSU) with heterogeneous computation and communication resources ([MeterCAD'20](#)).
  - Developed a vehicular edge computing ([VEC](#)) prototype supporting WiFi, DSRC, and LTE; compared their performance using real CAV applications ([HotEdge'20](#)).
  - Designed [HydraOne](#) from scratch, an indoor research and education platform. ([HotEdge'19](#)).
  - OpenVDAP: An Open Vehicular Data Analytics Platform ([ICDCS'18](#))

*May 2018 - December 2021*  
**Mentor:** Weisong Shi
  
- **Edge Computing Enabled Applications for Public Safety**  
*Wayne State University*

*January 2018 - December 2018*  
**Mentor:** Weisong Shi

- Propose SafeShareRide, an edge-based real-time attack detection system in ridesharing services ([SEC'18](#), [HotEdge'18](#)).
- Develop AutoVAPS, an edge-based reference architecture for privacy-preserving data sharing and access on law enforcement vehicles. ([CPSWEEK'18 Workshop](#))

## HONORS AND AWARDS

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- **Department Travel Award for Outstanding Conference Publications** 2023  
*Wayne State University*
- **RTSS Student Travel Grant** 2022  
*IEEE Real-Time Systems Symposium*
- **Department Travel Award for Outstanding Conference Publications** 2022  
*Wayne State University*
- **NSF ACM/IEEE Symposium on Edge Computing Student Travel Grant** 2019, 2018, 2021  
*National Science Foundation*
- **Top Ten Seniors Award** 2016  
*Xidian University*
- **First Prize, CETC-10 Literature Review Contest** 2016  
*CETC-10, Xidian University*

## TEACHING EXPERIENCE

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- **Guest lecture, Robot Platforms for CPS Research** 2024  
*University of Michigan, EECS-571*
- **Guest lecture, Building Predictable and Efficient System for Autonomous Vehicles/Robots** 2023  
*University of Michigan, EECS-571*
- **Seminar talk: Building Predictable and Efficient System for Autonomous Vehicles/Robots** 2024  
*University of North Texas*
- **Seminar talk: Building Predictable and Efficient System for Autonomous Vehicles/Robots** 2024  
*California Polytechnic State University*
- **Seminar talk: Introduction to Autonomous Driving** 2023  
*HensHack at University of Delaware*
- **Computing systems for connected and autonomous driving** 2022  
*UIUC physical AI group*
- **Teaching Assistant, Introduction to Java Programming** 2018  
*Wayne State University*

## MENTORING EXPERIENCE

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- **Sanjith Udupa** *Mentored: 2022/2023*  
*Novi High School student; now undergraduate at MIT* [first-authored paper](#)
- **Mingyu Guo** *Mentored: 2023*  
*Undergraduate at the University of Wisconsin–Madison; now Ph.D. at University of Delaware*
- **Yuchen Chueh** *Mentored: 2020*  
*Now Master's student at Carnegie Mellon University*
- **Justin Baskaran** *Mentored: 2018*  
*Backend Software Engineer at General Motors*

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**PROFESSIONAL SERVICES**

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- **Program Committee**, Workshop on Compute Platforms for Autonomous Vehicles (CAV), ASPLOS 2024
- **Program Committee**, The 2nd IEEE International Conference on Mobility: Operations, Services, and Technologies (MOST), 2024
- **Program Committee**, The 21th ACM Conference on Embedded Networked Sensor Systems (SenSys 2023) Posters & Demos
- **Reviewer**, IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR), 2024
- **Reviewer**, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2022/2023/2024
- **Reviewer**, IEEE International Conference on Robotics and Automation (ICRA), 2023
- **Web Chair**, The 30th Annual International Conference on Mobile Computing and Networking (MobiCom 2024)
- **Committee Member**, Technical Steering Committee of the Autoware Foundation, October 2022 - December 2023
- **Verified and Recognized Reviewer**: IEEE Communications Magazine, Proceedings of the IEEE, IEEE Transactions on Vehicular Technology, IEEE Vehicular Technology Magazine, IEEE Transactions on Services Computing, IEEE Internet of Things Journal, IEEE Network Magazine, IEEE Internet Computing, IEEE Open Journal of Circuits and Systems, IEEE Transactions on Network Science and Engineering, IEEE Transactions on Intelligent Transportation Systems, and IEEE Robotics and Automation Letters.

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**REFERENCES**

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**1. Kang G. Shin**

Kevin and Nancy O'Connor Professor of Computer Science  
University of Michigan  
Email: kgshin@umich.edu  
Phone: +1-734-763-0391  
*Relationship: Postdoc Mentor*

**2. Weisong Shi**

Alumni Distinguished Professor and Chair, Department of Computer and Information Sciences  
University of Delaware  
Email: weisong@udel.edu  
Phone: +1-302-831-7603  
*Relationship: PhD Advisor*

**3. Chengmo Yang**

Professor, Department of Electrical and Computer Engineering  
University of Delaware  
Email: chengmo@udel.edu  
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*Relationship: Collaborator*

**4. Yanzhi Wang**

Associate Professor, Electrical and Computer Engineering  
Northeastern University  
Email: yanz.wang@northeastern.edu  
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*Relationship: Collaborator*

**5. Marco Brocanelli**

Assistant Professor, Electrical and Computer Engineering

Ohio State University

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*Relationship: Collaborator*